

UNIVERSITY OF TWENTE.

Simple odd β -cycle inequalities for
binary polynomial optimization

Matthias Walter (Uni Twente)

Joint work with Alberto del Pia (Uni Wisconsin-Madison)



Let's SCIP it! A workshop to celebrate
20 years of SCIP, 2022



UNIVERSITY OF TWENTE.

Simple odd β -cycle inequalities for
binary polynomial optimization

Matthias Walter (Uni Twente)

Joint work with Alberto del Pia (Uni Wisconsin-Madison)



Let's SCIP it! A workshop to celebrate
20 years of SCIP, 2022



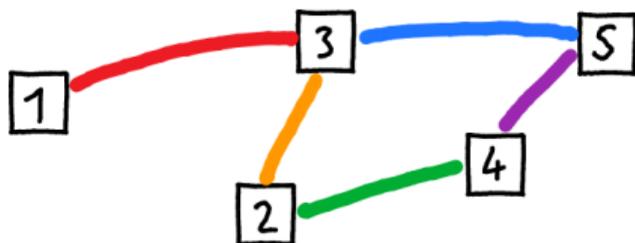
Definition – Boolean quadric polytope

[Padberg '88]

Let $G = (V, E)$ be a graph. The **boolean quadric polytope** of G is the polytope

$$\text{BQP}(G) := \text{conv} \{ (x, y) \in \{0, 1\}^V \times \{0, 1\}^E : y_{\{u,v\}} = x_u \cdot x_v \text{ for each edge } \{u, v\} \in E \}.$$

Example:



$$y_{\{1,3\}} = x_1 \cdot x_3$$

$$y_{\{2,3\}} = x_2 \cdot x_3$$

$$y_{\{2,4\}} = x_2 \cdot x_4$$

$$y_{\{3,5\}} = x_3 \cdot x_5$$

$$y_{\{4,5\}} = x_4 \cdot x_5$$

$$x_i \in \{0, 1\} \quad i=1, \dots, 5$$

Remarks:

- ▶ Equivalent to CUT polytope of related graph.
- ▶ Can be used to minimize a quadratic function $q(x)$ over $x \in \{0, 1\}^n$, also known as “quadratic unconstrained binary optimization”.
- ▶ Optimization over BQP is NP-hard in general.

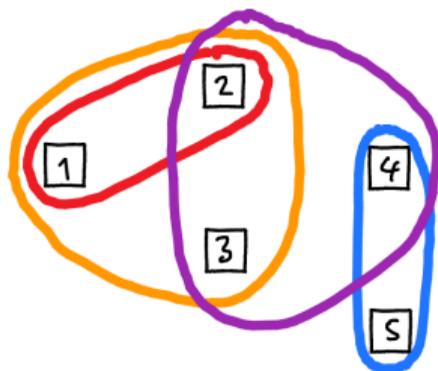
[Barahona, Mahjoub '86]

Definition – Multilinear polytope [Del Pia, Khajavirad '16; Buchheim, Crama, Rodríguez-Heck '16]

Let $G = (V, E)$ be a hypergraph. The multilinear polytope of G is the polytope

$$\text{ML}(G) := \text{conv} \left\{ (x, y) \in \{0, 1\}^V \times \{0, 1\}^E : y_e = \prod_{v \in e} x_v \text{ for each edge } \{u, v\} \in E \right\}.$$

Example:



$$y_{\{1,2\}} = x_1 \cdot x_2$$

$$y_{\{1,2,3\}} = x_1 \cdot x_2 \cdot x_3$$

$$y_{\{2,3,4\}} = x_2 \cdot x_3 \cdot x_4$$

$$y_{\{4,5\}} = x_4 \cdot x_5$$

Remarks:

- ▶ Can be used to minimize a polynomial function $p(x)$ over $x \in \{0, 1\}^n$, also known as “polynomial unconstrained binary optimization” or “pseudo-boolean optimization”.
- ▶ For each hyperedge $e = \{v_1, v_2, \dots, v_k\}$, we have the logic AND constraint $y_e = x_{v_1} \wedge x_{v_2} \wedge \dots \wedge x_{v_k}$.

Proposition – Standard relaxation [Fortet '60; Glover, Woolsey '74]

Let $G = (V, E)$ be a hypergraph. The polytope $SR(G)$ defined by

$$0 \leq y_e \leq x_v \leq 1 \quad \forall v \in e \in E \quad (1a)$$

$$y_e + \sum_{v \in e} (1 - x_v) \geq 1 \quad \forall e \in E \quad (1b)$$

yields an IP formulation, i.e., $SR(G) \cap \mathbb{Z}^{V+E} = ML(G) \cap \mathbb{Z}^{V+E}$.

Proposition – Standard relaxation [Fortet '60; Glover, Woolsey '74]

Let $G = (V, E)$ be a hypergraph. The polytope $SR(G)$ defined by

$$0 \leq y_e \leq x_v \leq 1 \quad \forall v \in e \in E \quad (1a)$$

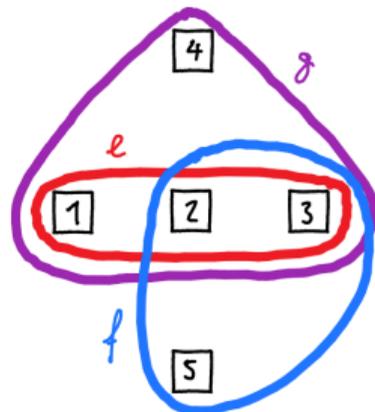
$$y_e + \sum_{v \in e} (1 - x_v) \geq 1 \quad \forall e \in E \quad (1b)$$

yields an IP formulation, i.e., $SR(G) \cap \mathbb{Z}^{V+E} = ML(G) \cap \mathbb{Z}^{V+E}$.

Berge cycle:

$v_1, e_1, v_2, e_2, \dots, v_k, e_k, v_1$ with:

- ▶ $v_i \in V$ are distinct nodes.
- ▶ $e_i \in E$ are distinct edges.
- ▶ $v_i \in e_{i-1} \cap e_i$ for each i



$$1 - e - 2 - f - 3 - g - 1$$

Proposition – Standard relaxation [Fortet '60; Glover, Woolsey '74]

Let $G = (V, E)$ be a hypergraph. The polytope $SR(G)$ defined by

$$0 \leq y_e \leq x_v \leq 1 \quad \forall v \in e \in E \quad (1a)$$

$$y_e + \sum_{v \in e} (1 - x_v) \geq 1 \quad \forall e \in E \quad (1b)$$

yields an IP formulation, i.e., $SR(G) \cap \mathbb{Z}^{V+E} = ML(G) \cap \mathbb{Z}^{V+E}$.

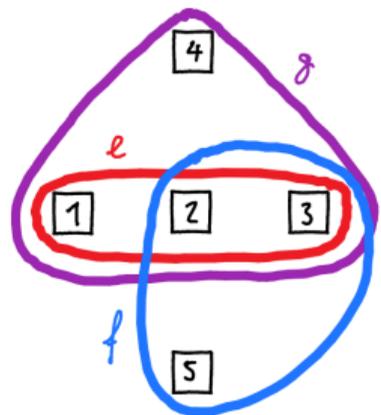
Theorem – Perfect formulation [Del Pia, Khajavirad '16; Buchheim, Crama, Rodríguez-Heck '16]

$SR(G) = ML(G)$ holds if and only if G is **Berge-acyclic**.

Berge cycle:

$v_1, e_1, v_2, e_2, \dots, v_k, e_k, v_1$ with:

- ▶ $v_i \in V$ are distinct nodes.
- ▶ $e_i \in E$ are distinct edges.
- ▶ $v_i \in e_{i-1} \cap e_i$ for each i



1 - e - 2 - f - 3 - g - 1

Proposition – Standard relaxation [Fortet '60; Glover, Woolsey '74]

Let $G = (V, E)$ be a hypergraph. The polytope $SR(G)$ defined by

$$0 \leq y_e \leq x_v \leq 1 \quad \forall v \in e \in E \quad (1a)$$

$$y_e + \sum_{v \in e} (1 - x_v) \geq 1 \quad \forall e \in E \quad (1b)$$

yields an IP formulation, i.e., $SR(G) \cap \mathbb{Z}^{V+E} = ML(G) \cap \mathbb{Z}^{V+E}$.

Theorem – Perfect formulation [Del Pia, Khajavirad '16; Buchheim, Crama, Rodríguez-Heck '16]

$SR(G) = ML(G)$ holds if and only if G is **Berge-acyclic**.

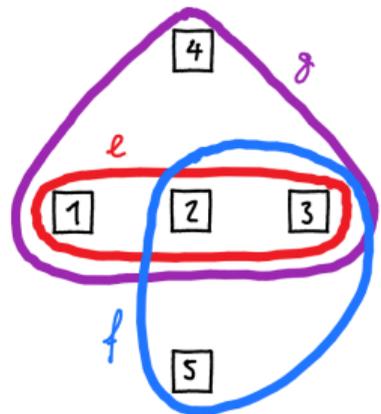
Remark:

- ▶ There exist several definitions of cycles in hypergraphs, such as Berge cycles, β -cycles, γ -cycles.

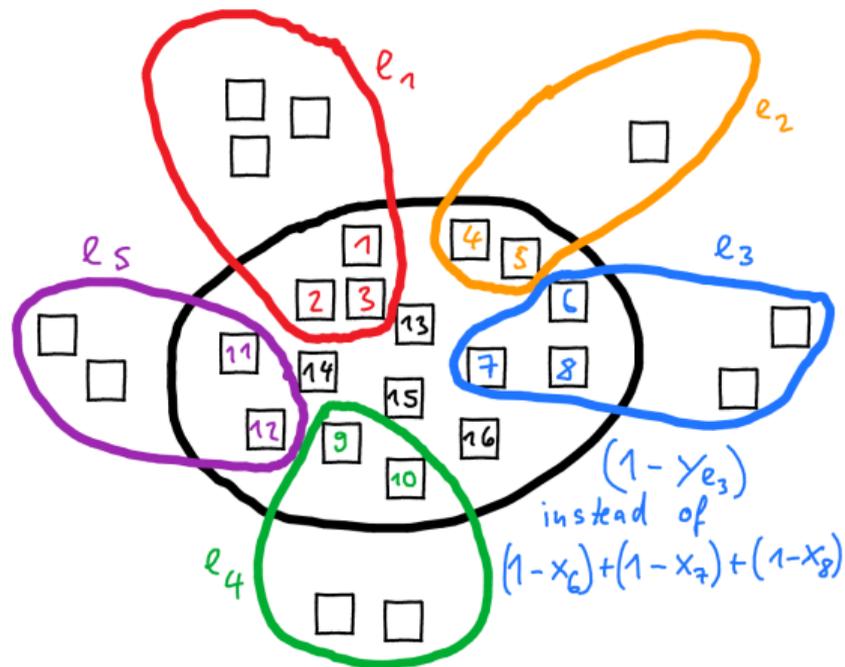
Berge cycle:

$v_1, e_1, v_2, e_2, \dots, v_k, e_k, v_1$ with:

- ▶ $v_i \in V$ are distinct nodes.
- ▶ $e_i \in E$ are distinct edges.
- ▶ $v_i \in e_{i-1} \cap e_i$ for each i



1 - e - 2 - f - 3 - g - 1



Definition – Flower relaxation

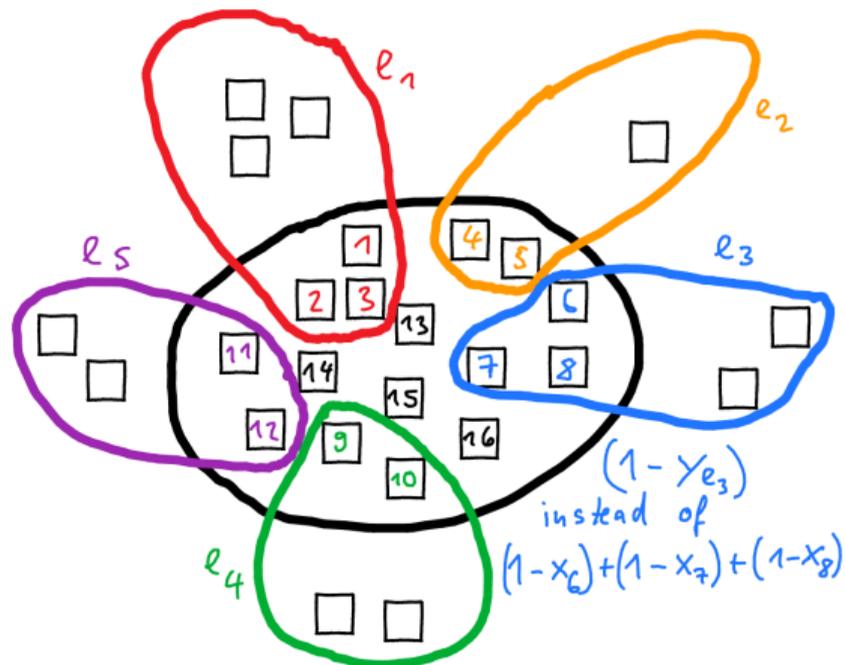
[Del Pia, Khajavirad '18]

The k -flower inequality centered at f with neighbors e_1, e_2, \dots, e_k is

$$y_f + \sum_{i=1}^k (1 - y_{e_i}) + \sum_{v \in R} (1 - x_v) \geq 1, \quad (2)$$

where $R := f \setminus \bigcup_{i=1}^k e_i$ contains all nodes of v that are not in a leaf. We denote by $\text{FR}(G)$ the standard relaxation $\text{SR}(G)$, augmented by all 1-flower and all 2-flower inequalities.

For comparison: $y_f + \sum_{v \in f} (1 - x_v) \geq 1 \quad (1b)$



Definition – Flower relaxation

[Del Pia, Khajavirad '18]

The k -flower inequality centered at f with neighbors e_1, e_2, \dots, e_k is

$$y_f + \sum_{i=1}^k (1 - y_{e_i}) + \sum_{v \in R} (1 - x_v) \geq 1, \quad (2)$$

where $R := f \setminus \bigcup_{i=1}^k e_i$ contains all nodes of v that are not in a leaf. We denote by FR(G) the standard relaxation SR(G), augmented by all 1-flower and all 2-flower inequalities.

For comparison: $y_f + \sum_{v \in f} (1 - x_v) \geq 1 \quad (1b)$

Special case and generalization:

- ▶ 1-flower inequalities were independently introduced as **2-link inequalities**. [Crama, Rodríguez-Heck '17]
- ▶ Flower inequalities can be generalized to **running intersection inequalities**. [Del Pia, Khajavirad '21]

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Definition 2. Consider a hypergraph $G = (V, E)$, let $C = v_1, e_1, v_2, \dots, v_m, e_m, v_1$ be a β -cycle in G , and let E^-, E^+ be a partition of $E(C)$ such that $k := |E^-|$ is odd and $e_1 \in E^-$. Let $D := \{e_{p+1}, e_{p+2}, \dots, e_m\}$, where e_p is the last edge in C that belongs to E^- . We denote by f_1, \dots, f_k the subsequence of e_1, \dots, e_m of the edges in E^- . Let $S_1 := (\cup_{e \in E^-} e) \setminus \cup_{e \in E^+} e$ and $S_2 := V(C) \setminus \cup_{e \in E^-} e$. With this notation in place, we make the following assumptions:

- (a) Every node $v \in \cup_{i=1}^m e_i$ is contained in at most two edges among e_1, \dots, e_m .
- (b) For every edge $e_i \in E^+ \setminus D$, every edge in E^- adjacent to e_i (if any) is either e_{i-1} or e_{i+1} .
- (c) No edge in D is adjacent to an edge f_i with i even.
- (d) At least one of the following two conditions holds:
 - (d1) For every $v \in S_1$, either v is contained in just one edge $e \in E^-$, or it is contained in two edges f_i, f_j with i odd and j even.
 - (d2) For every $e' \in E^-$ and $e'' \in D$ such that $e' \cap e'' \neq \emptyset$, then either $e' = e_1, e'' = e_m$ or $e' = e_p, e'' = e_{p+1}$.

We then define the odd β -cycle inequality corresponding to C and E^- as

$$\sum_{v \in S_1} z_v - \sum_{e \in E^-} z_e - \sum_{v \in S_2} z_v + \sum_{e \in E^+} z_e \leq |S_1| - |\{i \in \{1, \dots, m\} : e_i, e_{i+1} \in E^-\}| + \left\lfloor \frac{k}{2} \right\rfloor. \quad (2)$$

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Definition 2. Consider a hypergraph $G = (V, E)$, let $C = v_1, e_1, v_2, \dots, v_m, e_m, v_1$ be a β -cycle in G , and let E^-, E^+ be a partition of $E(C)$ such that $k := |E^-|$ is odd and $e_1 \in E^-$. Let $D := \{e_{p+1}, e_{p+2}, \dots, e_m\}$, where e_p is the last edge in C that belongs to E^- . We denote by f_1, \dots, f_k the subsequence of e_1, \dots, e_m of the edges in E^- . Let $S_1 := (\cup_{e \in E^-} e) \setminus \cup_{e \in E^+} e$ and $S_2 := V(C) \setminus \cup_{e \in E^-} e$. With this notation in place, we make the following assumptions:

- (a) Every node $v \in \cup_{i=1}^m e_i$ is contained in at most two edges among e_1, \dots, e_m .
- (b) For every edge $e_i \in E^+ \setminus D$, every edge in E^- adjacent to e_i (if any) is either e_{i-1} or e_{i+1} .
- (c) No edge in D is adjacent to an edge f_i with i even.
- (d) At least one of the following two conditions holds:
 - (d1) For every $v \in S_1$, either v is contained in just one edge $e \in E^-$, or it is contained in two edges f_i, f_j with i odd and j even.
 - (d2) For every $e' \in E^-$ and $e'' \in D$ such that $e' \cap e'' \neq \emptyset$, then either $e' = e_1, e'' = e_m$ or $e' = e_p, e'' = e_{p+1}$.

We then define the odd β -cycle inequality corresponding to C and E^- as

$$\sum_{v \in S_1} z_v - \sum_{e \in E^-} z_e - \sum_{v \in S_2} z_v + \sum_{e \in E^+} z_e \leq |S_1| - |\{i \in \{1, \dots, m\} : e_i, e_{i+1} \in E^-\}| + \left\lfloor \frac{k}{2} \right\rfloor. \quad (2)$$

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Definition 2. Consider a hypergraph $G = (V, E)$, let $C = v_1, e_1, v_2, \dots, v_m, e_m, v_1$ be a β -cycle in G , and let E^-, E^+ be a partition of $E(C)$ such that $k := |E^-|$ is odd and $e_1 \in E^-$. Let $D := \{e_{p+1}, e_{p+2}, \dots, e_m\}$, where e_p is the last edge in C that belongs to E^- . We denote by f_1, \dots, f_k the subsequence of e_1, \dots, e_m of the edges in E^- . Let $S_1 := (\cup_{e \in E^-} e) \setminus \cup_{e \in E^+} e$ and $S_2 := V(C) \setminus \cup_{e \in E^-} e$. With this notation in place, we make the following assumptions:

- (a) Every node $v \in \cup_{i=1}^m e_i$ is contained in at most two edges among e_1, \dots, e_m .
- (b) For every edge $e_i \in E^+ \setminus D$, every edge in E^- adjacent to e_i (if any) is either e_{i-1} or e_{i+1} .
- (c) No edge in D is adjacent to an edge f_i with i even.
- (d) At least one of the following two conditions holds:
 - (d1) For every $v \in S_1$, either v is contained in just one edge $e \in E^-$, or it is contained in two edges f_i, f_j with i odd and j even.
 - (d2) For every $e' \in E^-$ and $e'' \in D$ such that $e' \cap e'' \neq \emptyset$, then either $e' = e_1, e'' = e_m$ or $e' = e_p, e'' = e_{p+1}$.

We then define the odd β -cycle inequality corresponding to C and E^- as

$$\sum_{v \in S_1} z_v - \sum_{e \in E^-} z_e - \sum_{v \in S_2} z_v + \sum_{e \in E^+} z_e \leq |S_1| - |\{i \in \{1, \dots, m\} : e_i, e_{i+1} \in E^-\}| + \left\lfloor \frac{k}{2} \right\rfloor. \quad (2)$$

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Definition 2. Consider a hypergraph $G = (V, E)$, let $C = v_1, e_1, v_2, \dots, v_m, e_m, v_1$ be a β -cycle in G , and let E^-, E^+ be a partition of $E(C)$ such that $k := |E^-|$ is odd and $e_1 \in E^-$. Let $D := \{e_{p+1}, e_{p+2}, \dots, e_m\}$, where e_p is the last edge in C that belongs to E^- . We denote by f_1, \dots, f_k the subsequence of e_1, \dots, e_m of the edges in E^- . Let $S_1 := (\cup_{e \in E^-} e) \setminus \cup_{e \in E^+} e$ and $S_2 := V(C) \setminus \cup_{e \in E^-} e$. With this notation in place, we make the following assumptions:

- (a) Every node $v \in \cup_{i=1}^m e_i$ is contained in at most two edges among e_1, \dots, e_m .
 - (b) For every edge $e_i \in E^+ \setminus D$, every edge in E^- adjacent to e_i (if any) is either e_{i-1} or e_{i+1} .
 - (c) No edge in D is adjacent to an edge f_i with i even.
 - (d) At least one of the following two conditions holds:
 - (d1) For every $v \in S_1$, either v is contained in just one edge $e \in E^-$, or it is contained in two edges f_i, f_j with i odd and j even.
 - (d2) For every $e' \in E^-$ and $e'' \in D$ such that $e' \cap e'' \neq \emptyset$, then either $e' = e_1, e'' = e_m$ or $e' = e_p, e'' = e_{p+1}$.
- We then define the odd β -cycle inequality corresponding to C and E^- as

$$\sum_{v \in S_1} z_v - \sum_{e \in E^-} z_e - \sum_{v \in S_2} z_v + \sum_{e \in E^+} z_e \leq |S_1| - |\{i \in \{1, \dots, m\} : e_i, e_{i+1} \in E^-\}| + \left\lfloor \frac{k}{2} \right\rfloor. \quad (2)$$

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Let $G = (V, E)$ be a hypergraph. If there is a β -cycle C with a certain edge bipartition and some extra definitions satisfying some extra properties, then

⟨some inequality with complicated coefficients and complicated right-hand side⟩

is called **odd β -cycle inequality** and valid for $ML(G)$.

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Let $G = (V, E)$ be a hypergraph. If there is a β -cycle C with a certain edge bipartition and some extra definitions satisfying some extra properties, then

⟨some inequality with complicated coefficients and complicated right-hand side⟩

is called **odd β -cycle inequality** and valid for $ML(G)$.

Theorem – CG rank [Del Pia, Di Gregorio '19]

Odd β -cycle inequalities have Chvátal rank 2 (w.r.t. SR).

Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Let $G = (V, E)$ be a hypergraph. If there is a β -cycle C with a certain edge bipartition and some extra definitions satisfying some extra properties, then

⟨some inequality with complicated coefficients and complicated right-hand side⟩

is called **odd β -cycle inequality** and valid for $ML(G)$.

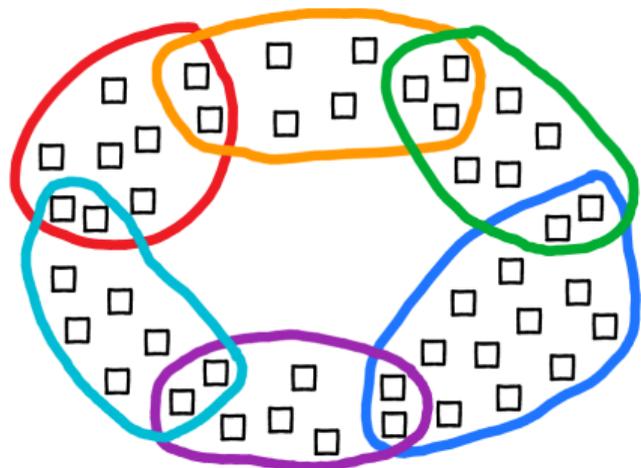
Theorem – CG rank [Del Pia, Di Gregorio '19]

Odd β -cycle inequalities have Chvátal rank 2 (w.r.t. SR).

Theorem – Perfection [Del Pia, Di Gregorio '19]

For **cyclic hypergraphs** G , $ML(G)$ is completely described by $FR(G)$ plus odd β -cycle inequalities.

Cyclic hypergraph:



Definition – Odd β -cycle inequalities

[Del Pia, Di Gregorio '19]

Let $G = (V, E)$ be a hypergraph. If there is a β -cycle C with a certain edge bipartition and some extra definitions satisfying some extra properties, then

⟨some inequality with complicated coefficients and complicated right-hand side⟩

is called **odd β -cycle inequality** and valid for $ML(G)$.

Theorem – CG rank [Del Pia, Di Gregorio '19]

Odd β -cycle inequalities have Chvátal rank 2 (w.r.t. SR).

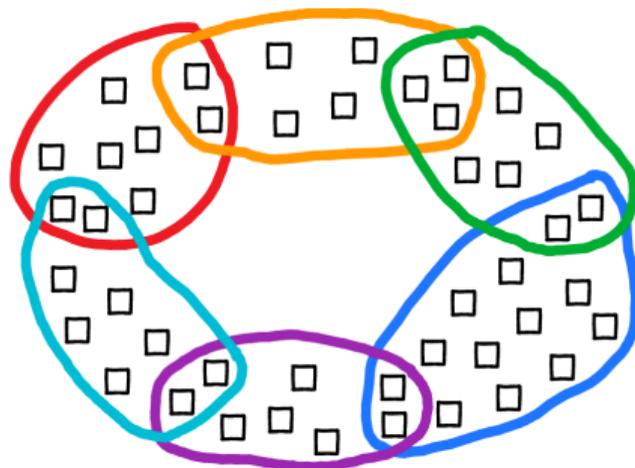
Theorem – Perfection [Del Pia, Di Gregorio '19]

For **cyclic hypergraphs** G , $ML(G)$ is completely described by $FR(G)$ plus odd β -cycle inequalities.

Theorem – Separation [Del Pia, Di Gregorio '19]

For **cyclic hypergraphs**, the separation problem for odd β -cycle inequalities can be solved in polynomial time.

Cyclic hypergraph:



Definition – Simple Odd β -cycle inequalities**[Del Pia, Walter '22]**

(see next slides)

Remark:

- ▶ The new definition yields weaker inequalities in general!

Theorem – CG rank**[Del Pia, Walter '22]**

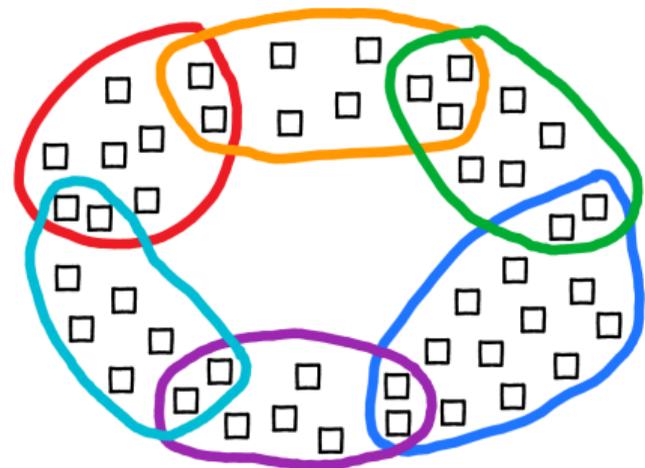
Simple odd β -cycle inequalities have Chvátal rank 2 (with respect to the standard relaxation SR).

Theorem – Perfection**[Del Pia, Walter '22]**

For **cyclic hypergraphs** G , $ML(G)$ is completely described by $FR(G)$ plus **simple** odd β -cycle inequalities.

Theorem – Separation**[Del Pia, Walter '22]**

For **arbitrary hypergraphs**, the separation problem for **simple** odd β -cycle inequalities can be solved in polynomial time.

Cyclic hypergraph:

We consider an edge sequence e, f, g with $U = e \cap f$, $W = f \cap g$:

Lemma – Building block inequalities

The following **building block inequalities** $s(x, y) \geq 0$ are valid for $FR(G)$.

$$2y_f - 1 + \sum_{u \in U} (1 - x_u) + \sum_{w \in W} (1 - x_w) + \sum_{v \in f \setminus (U \cup W)} (2 - 2x_v) \geq 0$$

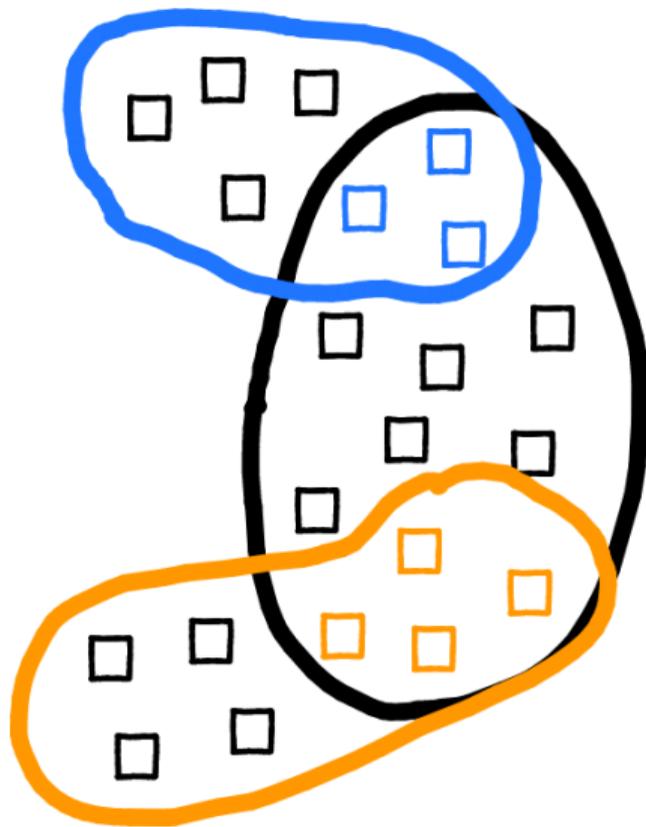
$$2y_f - 1 + (1 - y_e) + \sum_{w \in W} (1 - x_w) + \sum_{v \in f \setminus (U \cup W)} (2 - 2x_v) \geq 0$$

$$2y_f - 1 + \sum_{u \in U} (1 - x_u) + (1 - y_g) + \sum_{v \in f \setminus (U \cup W)} (2 - 2x_v) \geq 0$$

$$2y_f - 1 + (1 - y_e) + (1 - y_g) + \sum_{v \in f \setminus (U \cup W)} (2 - 2x_v) \geq 0$$

$$x_u - 2y_e + x_w \geq 0$$

$$x_v - y_e \geq 0$$



Simple Odd β -Cycle Inequalities

Example:

$$2\gamma_{e_1} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (2-2x_4) + (1-x_5) + (1-x_6) \geq 0$$

$$2\gamma_{e_8} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (1-x_{21}) \geq 0$$

$e_8, \text{ odd}$

$$2\gamma_{e_2} - 1 + (1-x_5) + (1-x_6) + (2-2x_7) + (1-\gamma_{e_3}) \geq 0$$

$e_2, \text{ odd}$

$$2\gamma_{e_7} - 1 + (1-x_{21}) + (2-2x_{19}) + (2-2x_{20}) + (1-\gamma_{e_6}) \geq 0$$

$e_7, \text{ odd}$

$e_6, \text{ even}$

$$x_{16} - \gamma_{e_6} \geq 0$$

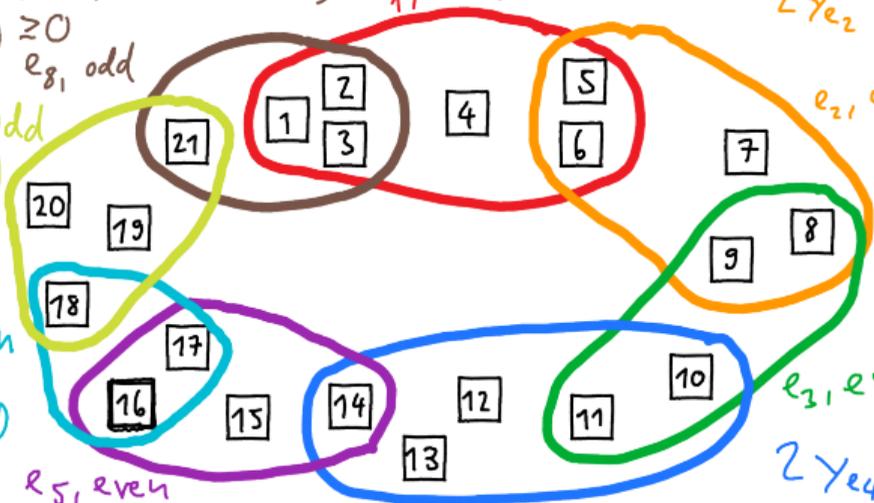
$e_5, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_4, \text{ odd}$

$e_3, \text{ even}$

$$2\gamma_{e_4} - 1 + (1-\gamma_{e_3}) + (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$



○

Example:

$$2\gamma_{e_1} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (2-2x_4) + (1-x_5) + (1-x_6) \geq 0$$

$$2\gamma_{e_8} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (1-x_{21}) \geq 0$$

$e_8, \text{ odd}$

$$2\gamma_{e_2} - 1 + (1-x_5) + (1-x_6) + (2-2x_7) + (1-\gamma_{e_3}) \geq 0$$

$e_2, \text{ odd}$

$$2\gamma_{e_7} - 1 + (1-x_{21}) + (2-2x_{19}) + (2-2x_{20}) + (1-\gamma_{e_6}) \geq 0$$

$e_7, \text{ odd}$

$$x_{16} - \gamma_{e_6} \geq 0$$

$e_6, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_5, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_4, \text{ odd}$

$$2\gamma_{e_4} - 1 + (1-\gamma_{e_3}) + (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$

$e_3, \text{ even}$

Validity arguments in general:

- Add building blocks along a cyclic walk such that overlapping terms add up to something even.

Example:

$$2\gamma_{e_1} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (2-2x_4) + (1-x_5) + (1-x_6) \geq 0$$

$$2\gamma_{e_8} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (1-x_{21}) \geq 0$$

$e_8, \text{ odd}$

$$2\gamma_{e_2} - 1 + (1-x_5) + (1-x_6) + (2-2x_7) + (1-\gamma_{e_3}) \geq 0$$

$e_2, \text{ odd}$

$$2\gamma_{e_7} - 1 + (1-x_{21}) + (2-2x_{19}) + (2-2x_{20}) + (1-\gamma_{e_6}) \geq 0$$

$e_7, \text{ odd}$

$e_6, \text{ even}$

$$x_{16} - \gamma_{e_6} \geq 0$$

$e_5, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_4, \text{ odd}$

$e_3, \text{ even}$

$$2\gamma_{e_4} - 1 + (1-\gamma_{e_3}) + (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$

○

Validity arguments in general:

- ▶ Add building blocks along a cyclic walk such that overlapping terms add up to something even.
- ▶ This yields a new valid inequality with only even coefficients.

Example:

$$2\gamma_{e_1} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (2-2x_4) + (1-x_5) + (1-x_6) \geq 0$$

$$2\gamma_{e_8} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (1-x_{21}) \geq 0$$

$e_8, \text{ odd}$

$$2\gamma_{e_2} - 1 + (1-x_5) + (1-x_6) + (2-2x_7) + (1-\gamma_{e_3}) \geq 0$$

$e_2, \text{ odd}$

$$2\gamma_{e_7} - 1 + (1-x_{21}) + (2-2x_{19}) + (2-2x_{20}) + (1-\gamma_{e_6}) \geq 0$$

$e_7, \text{ odd}$

$$x_{16} - \gamma_{e_6} \geq 0$$

$e_6, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

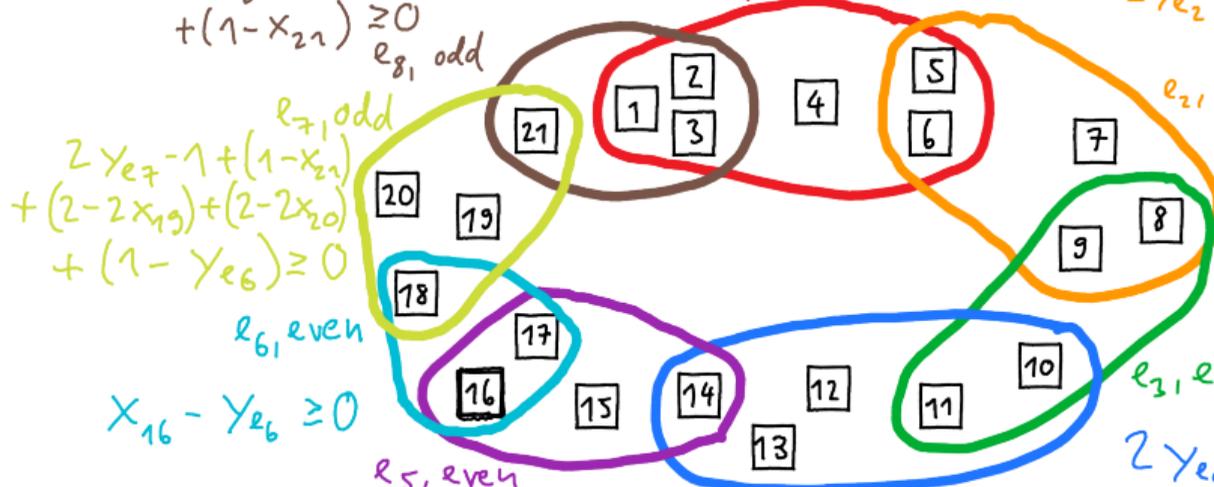
$e_5, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_4, \text{ odd}$

$$2\gamma_{e_4} - 1 + (1-\gamma_{e_3}) + (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$

$e_3, \text{ even}$



Validity arguments in general:

- ▶ Add building blocks along a cyclic walk such that overlapping terms add up to something even.
- ▶ This yields a new valid inequality with only even coefficients.
- ▶ If the first four building blocks occur an odd number of times, the right-hand side is odd.

Example:

$$2\gamma_{e_1} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (2-2x_4) + (1-x_5) + (1-x_6) \geq 0$$

$$2\gamma_{e_8} - 1 + (1-x_1) + (1-x_2) + (1-x_3) + (1-x_{21}) \geq 0$$

$e_8, \text{ odd}$

$$2\gamma_{e_2} - 1 + (1-x_5) + (1-x_6) + (2-2x_7) + (1-\gamma_{e_3}) \geq 0$$

$e_2, \text{ odd}$

$$2\gamma_{e_7} - 1 + (1-x_{21}) + (2-2x_{19}) + (2-2x_{20}) + (1-\gamma_{e_6}) \geq 0$$

$e_7, \text{ odd}$

$$x_{16} - \gamma_{e_6} \geq 0$$

$e_6, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_5, \text{ even}$

$$x_{16} - \gamma_{e_5} \geq 0$$

$e_4, \text{ odd}$

$$2\gamma_{e_4} - 1 + (1-\gamma_{e_3}) + (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$

$e_3, \text{ even}$

$$+ (2-2x_{12}) + (2-2x_{13}) + (1-\gamma_{e_5}) \geq 0$$

Validity arguments in general:

- ▶ Add building blocks along a cyclic walk such that overlapping terms add up to something even.
- ▶ This yields a new valid inequality with only even coefficients.
- ▶ If the first four building blocks occur an odd number of times, the right-hand side is odd.
- ▶ Hence, we can increase right-hand side by 1. (or: scale by $\frac{1}{2}$ and round rhs up)

Auxiliary graph:

- ▶ Auxiliary nodes (c, p) where c is a “connection point” ($V \cup E \cup \{e \cap f : e, f \in E\}$) and $p \in \{\pm 1\}$ is a parity.
- ▶ Auxiliary edges from (c, p) to (c', p') for building block inequality $s(x, y) \geq 0$ between connection points c and c' . Parities $p \neq p'$ if and only if one of first four inequalities.
- ▶ Length of edge: slack $s(\hat{x}, \hat{y})$ for given vector (\hat{x}, \hat{y}) .

Auxiliary graph:

- ▶ Auxiliary nodes (c, p) where c is a “connection point” $(V \cup E \cup \{e \cap f : e, f \in E\})$ and $p \in \{\pm 1\}$ is a parity.
- ▶ Auxiliary edges from (c, p) to (c', p') for building block inequality $s(x, y) \geq 0$ between connection points c and c' . Parities $p \neq p'$ if and only if one of first four inequalities.
- ▶ Length of edge: slack $s(\hat{x}, \hat{y})$ for given vector (\hat{x}, \hat{y}) .

Lemma – Reduction to shortest odd cycle problem

[Del Pia, Walter '22]

Walks from (c, p) to $(c, -p)$ of length less than 1 \iff simple odd β -cycle inequality violated by (\hat{x}, \hat{y})

Auxiliary graph:

- ▶ Auxiliary nodes (c, p) where c is a “connection point” ($V \cup E \cup \{e \cap f : e, f \in E\}$) and $p \in \{\pm 1\}$ is a parity.
- ▶ Auxiliary edges from (c, p) to (c', p') for building block inequality $s(x, y) \geq 0$ between connection points c and c' . Parities $p \neq p'$ if and only if one of first four inequalities.
- ▶ Length of edge: slack $s(\hat{x}, \hat{y})$ for given vector (\hat{x}, \hat{y}) .

Lemma – Reduction to shortest odd cycle problem

[Del Pia, Walter '22]

Walks from (c, p) to $(c, -p)$ of length less than 1 \iff simple odd β -cycle inequality violated by (\hat{x}, \hat{y})

Consequence:

Theorem – Separation algorithm

[Del Pia, Walter '22]

Let $G = (V, E)$ be a hypergraph and let $(\hat{x}, \hat{y}) \in \text{FR}(G)$. The separation problem for simple odd β -cycle inequalities can be solved in time $\mathcal{O}(|E|^5 + |V|^2 \cdot |E|)$.

Auxiliary graph:

- ▶ Auxiliary nodes (c, p) where c is a “connection point” ($V \cup E \cup \{e \cap f : e, f \in E\}$) and $p \in \{\pm 1\}$ is a parity.
- ▶ Auxiliary edges from (c, p) to (c', p') for building block inequality $s(x, y) \geq 0$ between connection points c and c' . Parities $p \neq p'$ if and only if one of first four inequalities.
- ▶ Length of edge: slack $s(\hat{x}, \hat{y})$ for given vector (\hat{x}, \hat{y}) .

Lemma – Reduction to shortest odd cycle problem

[Del Pia, Walter '22]

Walks from (c, p) to $(c, -p)$ of length less than 1 \iff simple odd β -cycle inequality violated by (\hat{x}, \hat{y})

Consequence:

Theorem – Separation algorithm

[Del Pia, Walter '22]

Let $G = (V, E)$ be a hypergraph and let $(\hat{x}, \hat{y}) \in \text{FR}(G)$. The separation problem for simple odd β -cycle inequalities can be solved in time $\mathcal{O}(|E|^5 + |V|^2 \cdot |E|)$.

Proof:

- ▶ By the lemma above, it suffices to run Dijkstra's algorithm once for per connection point. □

Implementation:

- ▶ Plugin for SCIP solver framework that inspects all AND constraints and builds hypergraph G .
- ▶ Separation is done by increasing complexity:
 - ① Violated inequalities from $SR(G)$.
 - ② Violated 1-flower inequalities.
 - ③ Violated 2-flower inequalities.
 - ④ Violated simple odd β -cycle inequalities.



Implementation:

- ▶ Plugin for SCIP solver framework that inspects all AND constraints and builds hypergraph G .
- ▶ Separation is done by increasing complexity:
 - ① Violated inequalities from $SR(G)$.
 - ② Violated 1-flower inequalities.
 - ③ Violated 2-flower inequalities.
 - ④ Violated simple odd β -cycle inequalities.

Instances:

- ① Image restoration instances from computer vision. [used by Crama, Rodríguez-Heck '17]
 - ② Low autocorrelated binary sequence problem from POLIP / MINLPLib benchmark libraries for polynomial / mixed-integer nonlinear optimization. [used by Del Pia, Di Gregorio '21]
- ▶ For both, the maximum polynomial degree is 4, i.e., $|e| \leq 4$ for all $e \in E$.



Implementation:

- ▶ Plugin for SCIP solver framework that inspects all AND constraints and builds hypergraph G .
- ▶ Separation is done by increasing complexity:
 - ① Violated inequalities from $SR(G)$.
 - ② Violated 1-flower inequalities.
 - ③ Violated 2-flower inequalities.
 - ④ Violated simple odd β -cycle inequalities.

Instances:

- ① Image restoration instances from computer vision. [used by Crama, Rodríguez-Heck '17]
 - ② Low autocorrelated binary sequence problem from POLIP / MINLPLib benchmark libraries for polynomial / mixed-integer nonlinear optimization. [used by Del Pia, Di Gregorio '21]
- ▶ For both, the maximum polynomial degree is 4, i.e., $|e| \leq 4$ for all $e \in E$.

Experiment:

- ▶ Disable all other solver features, i.e., general-purpose cutting planes, presolve (except for linearization of the polynomial), symmetry breaking, restarts, heuristics.
- ▶ Compare obtained dual bounds to best known primal solution.
- ▶ Question to answer: **How much gap can these inequalities close?**



Table: Remaining gap (in %) and computation time to compute the dual bounds of different relaxations.

Image	$ V $	$ E $	Standard		1-flower		2-flower		S. odd β -cycle		SCIP cuts	
10×10	100	534	69.30 %	0.1 s	10.33 %	0.3 s	10.33 %	0.3 s	0.0 %	1.9 s	18.69 %	1.5 s
10×15	150	838	43.84 %	0.3 s	8.85 %	0.7 s	8.85 %	0.7 s	0.0 %	3.3 s	12.87 %	1.9 s
15×15	225	1275	63.00 %	0.7 s	12.80 %	2.4 s	12.80 %	2.4 s	0.0 %	5.3 s	22.47 %	7.1 s
15×20	300	1731	38.75 %	1.1 s	0.0 %	1.1 s	0.0 %	1.1 s	0.0 %	1.4 s	8.56 %	4.8 s
20×20	400	2353	39.46 %	1.7 s	0.14 %	2.8 s	0.14 %	2.8 s	0.0 %	4.8 s	17.86 %	24.2 s
20×25	500	2978	41.48 %	3.2 s	3.86 %	3.9 s	3.86 %	3.9 s	0.11 %	15.1 s	23.19 %	16.0 s
25×25	625	3718	41.00 %	2.9 s	0.26 %	5.2 s	0.26 %	5.2 s	0.04 %	17.1 s	11.80 %	12.5 s

Remark:

- Shown are averages over the 15 instances for each image size.

Table: Remaining gap (in %) and computation time to compute the dual bounds of different relaxations.

Image	V	E	Standard		1-flower		2-flower		S. odd β -cycle		SCIP cuts	
10 × 10	100	534	69.30 %	0.1 s	10.33 %	0.3 s	10.33 %	0.3 s	0.0 %	1.9 s	18.69 %	1.5 s
10 × 15	150	838	43.84 %	0.3 s	8.85 %	0.7 s	8.85 %	0.7 s	0.0 %	3.3 s	12.87 %	1.9 s
15 × 15	225	1275	63.00 %	0.7 s	12.80 %	2.4 s	12.80 %	2.4 s	0.0 %	5.3 s	22.47 %	7.1 s
15 × 20	300	1731	38.75 %	1.1 s	0.0 %	1.1 s	0.0 %	1.1 s	0.0 %	1.4 s	8.56 %	4.8 s
20 × 20	400	2353	39.46 %	1.7 s	0.14 %	2.8 s	0.14 %	2.8 s	0.0 %	4.8 s	17.86 %	24.2 s
20 × 25	500	2978	41.48 %	3.2 s	3.86 %	3.9 s	3.86 %	3.9 s	0.11 %	15.1 s	23.19 %	16.0 s
25 × 25	625	3718	41.00 %	2.9 s	0.26 %	5.2 s	0.26 %	5.2 s	0.04 %	17.1 s	11.80 %	12.5 s

Remark:

- Shown are averages over the 15 instances for each image size.

Observations – Image Restoration Instances

[Del Pia, Walter '22]

- 1-flower inequalities close a lot of gap already.
- 2-flower inequalities were never violated after adding 1-flowers.
- Simple odd β -cycle inequalities close almost all of the remaining gap.
- General-purpose cutting planes of SCIP are outperformed.

Table: Remaining gap (in %) and computation time to compute the dual bounds of different relaxations.

Instance	V	E	Standard		1-flower = 2-flower		S. odd β -cycle		SCIP cuts	
20-05	20	187	884.62 %	0.0 s	310.10 %	0.0 s	228.37 %	0.2 s	458.65 %	1.1 s
20-10	20	813	1428.61 %	0.2 s	519.41 %	0.6 s	365.8 %	59.0 s	1174.08 %	0.9 s
20-15	20	1474	1564.03 %	0.8 s	570.87 %	2.1 s	405.3 %	367.0 s	1374.16 %	1.4 s
25-06	25	382	1116.67 %	0.1 s	400.00 %	0.2 s	276.04 %	2.2 s	760.52 %	0.9 s
25-13	25	1757	1518.46 %	0.9 s	553.51 %	2.2 s	391.1 %	680.0 s	1344.46 %	2.3 s
25-19	25	3015	1645.87 %	2.3 s	602.50 %	6.9 s	\leq 428.67 %	$>$ 1 h	1518.22 %	3.8 s
25-25	25	3652	1730.76 %	3.0 s	633.80 %	9.0 s	\leq 454.81 %	$>$ 1 h	1573.28 %	6.8 s
30-04	30	193	633.33 %	0.0 s	211.11 %	0 s	211.11 %	0.0 s	223.46 %	1.2 s
30-08	30	896	1308.67 %	0.2 s	473.44 %	0.5 s	330.79 %	15.4 s	1035.81 %	1.1 s
30-15	30	2914	1598.37 %	1.2 s	584.75 %	4.1 s	414.39 %	2357.0 s	1428.35 %	4.5 s
30-23	30	5346	1717.31 %	3.5 s	630.39 %	11.8 s	\leq 468.46 %	$>$ 1 h	1634.17 %	7.6 s
30-30	30	6382	1782.08 %	4.8 s	653.86 %	18.1 s	\leq 576.22 %	$>$ 1 h	1696.71 %	14.3 s
35-04	35	228	633.33 %	0.0 s	210.94 %	0 s	210.94 %	0.0 s	238.28 %	1.2 s
35-09	35	1346	1417.93 %	0.4 s	516.48 %	1.0 s	362.92 %	59.1 s	1164.69 %	2.1 s
35-18	35	4967	1652.86 %	3.3 s	605.63 %	10.9 s	\leq 436.68 %	$>$ 1 h	1577.31 %	8.0 s
35-26	35	8312	1738.75 %	9.1 s	638.56 %	36.4 s	\leq 543.43 %	$>$ 1 h	1666.42 %	19.0 s
40-05	40	407	884.62 %	0.0 s	310.26 %	0.1 s	228.21 %	0 s	505.98 %	1.8 s
40-10	40	2013	1498.58 %	0.6 s	547.79 %	2.0 s	386.3 %	139.0 s	1289.21 %	3.3 s
40-30	40	7203	1790.20 %	21.1 s	658.76 %	94.1 s	unknown	$>$ 1 h	1757.06 %	42.5 s
40-40	40	15344	2246.31 %	33.7 s	839.29 %	202.0 s	unknown	$>$ 1 h	2195.81 %	65.4 s

Table: Remaining gap (in %) and computation time to compute the dual bounds of different relaxations.

Instance	V	E	Standard		1-flower = 2-flower		S. odd β -cycle		SCIP cuts	
45-05	45	462	882.77 %	0.1 s	309.46 %	0 s	227.62 %	0 s	514.98 %	2.9 s
45-11	45	2768	1558.63 %	1.1 s	571.21 %	3.6 s	403.78 %	392.0 s	1415.96 %	5.9 s
45-23	45	10731	1790.52 %	14.4 s	659.88 %	63.6 s	\leq 575.22 %	$>$ 1 h	1754.46 %	34.7 s
45-34	45	18303	3270.63 %	47.1 s	1252.4 %	348.0 s	unknown	$>$ 1 h	3216.41 %	94.2 s
45-45	45	21948	54 456.45 %	94.0 s	21 736.22 %	647.0 s	unknown	$>$ 1 h	53 662.93 %	119.0 s
50-06	50	832	1116.67 %	0.2 s	400.00 %	0.3 s	275.46 %	3.9 s	794.72 %	1.8 s
50-13	50	4407	1616.87 %	2.4 s	593.25 %	8.6 s	420.29 %	3131.0 s	1499.09 %	8.0 s
50-25	50	14362	2133.10 %	26.3 s	797.19 %	195.0 s	unknown	$>$ 1 h	2094.17 %	40.9 s
50-38	50	25396	39 284.44 %	107.0 s	15 696.67 %	1241.0 s	unknown	$>$ 1 h	38 675.21 %	219.0 s
50-50	50	30221	65 563.27 %	163.0 s	26 178.91 %	1424.0 s	unknown	$>$ 1 h	64 675.26 %	206.0 s
55-06	55	922	1124.83 %	0.2 s	403.36 %	0.4 s	277.94 %	4.3 s	804.18 %	2.1 s
55-14	55	5735	1687.63 %	4.2 s	621.19 %	15.3 s	\leq 441.43 %	$>$ 1 h	1608.75 %	10.3 s
55-28	55	19592	12 541.35 %	63.7 s	7270.68 %	231.0 s	unknown	$>$ 1 h	12 352.26 %	96.9 s
55-41	55	33013	49 516.78 %	189.0 s	\leq 26 840.37 %	$>$ 1 h	unknown	$>$ 1 h	48 682.01 %	403.0 s
55-55	55	40087	77 649.06 %	320.0 s	\leq 35 170.20 %	$>$ 1 h	unknown	$>$ 1 h	76 351.19 %	507.0 s
60-08	60	1976	1409.51 %	0.6 s	514.49 %	1.7 s	361.20 %	48.3 s	1227.38 %	3.7 s
60-15	60	7234	1662.86 %	6.8 s	610.75 %	27.5 s	\leq 435.55 %	$>$ 1 h	1610.77 %	15.9 s
60-30	60	24720	147 684.48 %	116.0 s	97 525.37 %	1685.0 s	unknown	$>$ 1 h	145 471.15 %	234.0 s
60-45	60	43129	58 469.68 %	350.0 s	32 242.86 %	2186.0 s	unknown	$>$ 1 h	57 950.54 %	458.0 s
60-60	60	51970	94 731.68 %	570.0 s	\leq 75 083.58 %	$>$ 1 h	unknown	$>$ 1 h	93 319.83 %	$>$ 1 h

Observations – Low Autocorrelated Binary Sequences

[Del Pia, Walter '22]

- ▶ 1-flower inequalities close a lot of gap already.
- ▶ 2-flower inequalities were never violated after adding 1-flowers.
- ▶ General-purpose cutting planes of SCIP are outperformed.

Observations – Low Autocorrelated Binary Sequences

[Del Pia, Walter '22]

- ▶ Extremely large gaps in general.
- ▶ 1-flower inequalities close a lot of gap already.
- ▶ 2-flower inequalities were never violated after adding 1-flowers.
- ▶ General-purpose cutting planes of SCIP are outperformed.

Observations – Low Autocorrelated Binary Sequences

[Del Pia, Walter '22]

- ▶ Extremely large gaps in general.
- ▶ Hypergraphs are quite dense.
- ▶ 1-flower inequalities close a lot of gap already.
- ▶ 2-flower inequalities were never violated after adding 1-flowers.
- ▶ Simple odd β -cycle inequalities are (currently) too expensive.
- ▶ General-purpose cutting planes of SCIP are outperformed.

Observations – Low Autocorrelated Binary Sequences

[Del Pia, Walter '22]

- ▶ Extremely large gaps in general.
- ▶ Hypergraphs are quite dense.
- ▶ 1-flower inequalities close a lot of gap already.
- ▶ 2-flower inequalities were never violated after adding 1-flowers.
- ▶ Simple odd β -cycle inequalities are (currently) too expensive.
- ▶ General-purpose cutting planes of SCIP are outperformed.

Remark:

- ▶ Implementation of 2-flower separation was carefully checked for correctness :-)

Conclusions – Future Research Directions

[Del Pia, Walter '22]

- ▶ New inequalities are the right relaxation for separation.
- ▶ Nice theoretical properties remain!
- ▶ Strengthening of generated inequalities should be possible.
- ▶ Auxiliary graph is of polynomial size, but $\mathcal{O}(|E|^2 + |V|)$ nodes and $\mathcal{O}(|E|^3 + |E| \cdot |V|)$ edges is not exactly small in practice.

Conclusions – Future Research Directions

[Del Pia, Walter '22]

- ▶ New inequalities are the right relaxation for separation.
- ▶ Nice theoretical properties remain!
- ▶ Strengthening of generated inequalities should be possible.
- ▶ Auxiliary graph is of polynomial size, but $\mathcal{O}(|E|^2 + |V|)$ nodes and $\mathcal{O}(|E|^3 + |E| \cdot |V|)$ edges is not exactly small in practice.

Good news:

- ▶ Preliminary results on using a smaller auxiliary graph \rightsquigarrow expect drastic reduction of running time.

Conclusions – Future Research Directions**[Del Pia, Walter '22]**

- ▶ New inequalities are the right relaxation for separation.
- ▶ Nice theoretical properties remain!
- ▶ Strengthening of generated inequalities should be possible.
- ▶ Auxiliary graph is of polynomial size, but $\mathcal{O}(|E|^2 + |V|)$ nodes and $\mathcal{O}(|E|^3 + |E| \cdot |V|)$ edges is not exactly small in practice.

Good news:

- ▶ Preliminary results on using a smaller auxiliary graph \rightsquigarrow expect drastic reduction of running time.

Happy Birthday SCIP!